

Volume 8, Issue 2, Pages 33-40, April-June 2024

An Innovative Guidotronic Bot with Integrated LiDAR and AI Voice Assistance

Aswin N.^{1*}, John Teni Jio F.², Pragnesh M.³ & Biju George G.⁴

¹⁻³UG student, ⁴Assistant Professor, ¹⁻⁴Department of Electronics and Communication Engineering, Stella Mary's College of Engineering, Kanyakumari, Tamil Nadu, India. Email: aswin21092002@gmail.com*



DOI: https://doi.org/10.46759/IIJSR.2024.8204

Copyright © 2024 Aswin N. et al. This is an open access article distributed under the terms of the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original author and source are credited.

Article Received: 11 February 2024

Article Accepted: 23 April 2024

Article Published: 30 April 2024

ABSTRACT

This research paper discusses the futuristic combination of LiDAR technology and Guidotronic Bot with AI Voice Assistance to improve robotic systems. AI Voice Assistance launches a new era of human-machine interaction. Today, intuitive communication and robot integration are crucial. This section discusses how AI Voice Assistance improves user experience and how people will soon be able to talk to robots in natural language. This will set the stage for Guidotronic Bot implementation discussions. This study shows the Guidotronic Bot, which can multitask without human assistance. We observe it and its effects in various situations. The integration method integrates LiDAR technology with the Guidotronic Bot's infrastructure to enable real-time mapping and vision. Accurate three-dimensional mapping from LiDAR sensors helps you avoid obstacles and navigate rough terrain. The integrated algorithm simplifies Guidotronic Bot, LiDAR sensor, and AI Voice Assistance system collaboration by combining sensors and making decisions. The bot uses AI algorithms to translate voice commands, use LiDAR for environmental data, and drive itself. This integration should improve navigation, awareness of surroundings, and voice control. This research expands robotic systems and prepares for future advances in human-robot interaction. Combining the Guidotronic Bot with LiDAR and AI Speech Recognition opens up new ways to navigate, interact with smart home devices, and work.

Keywords: Guidotronic bot; LiDAR sensor; AI algorithms; Integration; Voice assistance; Voice command; Navigation.

1. Introduction

Voice assistant systems have become increasingly popular and widely used as a result of recent developments in artificial intelligence (AI), which have contributed to their increased prevalence [1]. These technological advancements have brought about a significant change in the manner in which individuals make use of their preferred electronic devices. In order to provide an exceptional user experience in terms of data interaction, device control, and task completion, these systems consistently employ state-of-the-art conversational agents [2]. This is accomplished through the utilization of a natural communication platform. On the other hand, popular voice assistants demonstrate commendable proficiency in comprehending and providing responses to inquiries; however, they are not adequate in addressing spatial challenges and other practical issues that may arise. In the research that is presented in this article, an innovative approach to improving voice assistance systems is proposed. This approach involves the combination of robotics, laser mapping technology, artificial intelligence, and robotics. This creative approach is intended to circumvent the problem that is currently being faced [3]. In comparison to its predecessors, Guidotronic Bot stands out due to the remarkable functionalities that it possesses. These include the ability to respond in a manner that is natural-sounding, to comprehend the questions that are posed by users, and to interact with them. Using laser light, LiDAR is the most effective technology for determining the distance between you and an object. This is accomplished through the incorporation of laser light. The robot's sensory capabilities are improved as a result of this functionality, which gives it the ability to dynamically perceive its surroundings [4]. The system is able to acquire a more comprehensive understanding of the user's intentions and the surrounding context in which they are conveyed as a result of the incorporation of artificial intelligence techniques such as machine learning and deep learning. The combination of Guidotronic Bot and LiDAR technology has the potential



to be utilized in a variety of applications, one of which is the improvement of human speech in circumstances that are sensitive to context [5]. The capability of a system to monitor the precise location of an individual while this operation is being carried out makes it possible for the system to perform enhanced object recognition, location-based assistance, and contextual data presentation [6]. The goal is to build a verbal robot that is capable of comprehending human speech, navigating its surroundings with the help of LiDAR technology, and carrying out commands with the assistance of artificial intelligence.

2. Related Works

Recent developments in artificial intelligence (AI) and LiDAR technologies, which are discussed in this article, have made it possible to integrate them in a seamless manner [7]. The voice assistance technology has also been improved in order to further guarantee that the responses to the driver's spoken inquiries are accurate and delivered in a timely manner [8]. Now, let's take a look at the most noteworthy additions that have been made in each category: The utilization of virtual assistants like Alexa and Google Assistant is one of the scenarios that has demonstrated the effectiveness of natural language understanding and answer generation [9]. Other scenarios have also demonstrated the power of these capabilities. There is no doubt that the incorporation of voice assistants into Apple products results in increased productivity and a more structured approach to communication [10].

Secondly, a look at the LiDAR technology that is being used for autonomous vehicles: While conducting research on self-driving cars, there are a number of tasks that need to be completed, such as ensuring accurate measurements and optimizing real-time processing. LiDAR technology has made it much simpler for self-driving cars to see and locate themselves [11]. This is because the technology allows them to see and determine their location. Numerous opportunities have surfaced as a consequence of the widespread implementation of indoor mapping systems that are based on LiDAR in commercial environments [12]. Among these are the simplification of the tracking of industrial assets and the facilitation of the navigation of indoor spaces for individuals who have low or no vision. The development of new natural language processing (NLP) models, such as BERT and GPT, which were jointly developed by Google and OpenAI, has had a significant impact on the advancements that have been made in NLP generation and comprehension [13].

Deep learning, reinforcement learning, and supervised learning are three methodological approaches that can be utilized by artificial intelligence (AI) systems in order to acquire knowledge from vast amounts of data. These methods allow for continuous improvement. The researchers' interest has been piqued by the prospect of discovering a method to enhance the spatial intelligence of voice assistants [14]. There have been significant advancements in this field, and one example of this is the proliferation of voice assistants that are able to provide recommendations and directions based on the physical location of the user [15]. Multimodal interfaces have been developed by developers in order to facilitate the integration of a variety of forms of input, including voice interaction, gesture recognition, spatial orientation, and other forms of input respectively [16]. When you do this, it is much simpler to begin things in a manner that is more realistic, engaging, and laid-back. The new approach to localization and voice assistance that makes use of artificial intelligence, LiDAR, Guidotronic Bot, and real-time localization is a significant departure from the research that was done in the past. This is due to the fact that many



things have changed. It is possible to tailor it to specific contexts and it gives the impression of personal agency. This cutting-edge technology combines the best aspects of a number of different technologies in order to provide a novel means of human-computer interaction.

3. Proposed System

In order to address the problem of contextual awareness, which occurs when the assistive system is comparable to its environmental counterpart, the coordination of artificial intelligence with a guiding robot through the use of a laser range finder is utilized. By utilizing the complementary characteristics of the two innovations, this merger has the potential to create opportunities for applications that can be customized to meet specific needs. These applications will provide a more accurate understanding of the dynamics of the physical world.

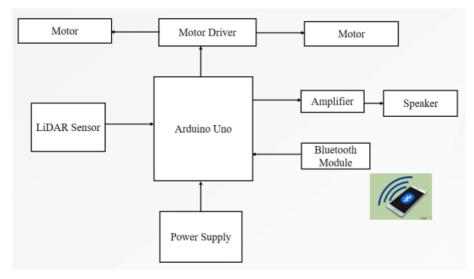


Figure 1. Block Diagram

With the help of natural language processing (NLP) algorithms, artificial intelligence (AI) algorithms, and LiDAR sensor technology, the Guidotronic Bot becomes a very advanced conversational agent that can do many different things. By using the most advanced natural language processing models to understand the questions users ask, figure out what those users are trying to say, and come up with the right answers, this system can provide trustworthy interaction. Lasers are used by the LiDAR Sensor Module of this robot to measure distances and make three-dimensional maps of the terrain. This gives the module very accurate spatial awareness. With this feature added, the bot can now recognize obstacles, move through different environments, and respond in a way that makes sense in that context.

The bot's contextual awareness, speech synthesis, and language understanding all got better over time thanks to the algorithms that were trained on datasets of user interactions. Over the course of years, these changes got better. Neurological networks, which can do things like object classification, scene segmentation, and spatial reasoning, make it safe for the bot to move around in real spaces. With the help of artificial intelligence and light-based localization and mapping (LiDAR), the Guidotronic Bot can do a lot of different things. Some of these services are better accessibility, location-based help, responses that make sense in the given situation, and real-time navigation. The system can help people find the best way to get around whether they are inside or outside of a building by using



three-dimensional data to learn about their preferences and the space around them. Users can get around more easily when this feature is available. Voice commands through the bot can help people who are blind or have low vision get information about objects, directions, and ways to get around.

The bot can work because of a network of parts that depend on each other. The Arduino Uno is in charge of sending output signals, processing data from sensors, and controlling motor functions. Meanwhile, the LiDAR sensor is in charge of finding obstacles and figuring out how far away they are. There are two important parts that turn electrical energy into motion: the motor and the motor driver. This has to be done for the bot to be able to follow the instructions sent by the Arduino Uno. The Bluetooth Module is what lets you send data wirelessly and control devices from afar. Furthermore, the Power Supply is in charge of providing all the parts with the electricity they need. Using the amplifier and speaker together makes it easier to talk to each other. The speaker makes sure that the microphone picks up the sounds that come in from the Arduino Uno and makes them louder so that they can be used for feedback or communication. This feature is necessary for the virtual assistant that is powered by artificial intelligence because it lets the bot talk to people and send them audio data.

4. Results and Discussion

When it comes to conversation, the Guidotronic Bot is very good at it. It also has great accessibility features and is very aware of its surroundings. Cutting edge artificial intelligence and LiDAR technology work together to make these features possible. The platform is very flexible and easy to change because it has motors, sensors, processors, and communication modules available. As a result, this opens the door to many uses, including real-time navigation and interactions that know what they're doing.

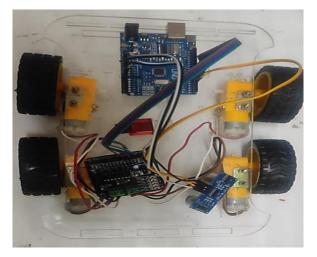


Figure 2. Hardware Prototype

The Guidotronic Bot is an impressive robot that, as a result of its integration of artificial intelligence, LiDAR, and voice assistance technologies, provides a wide range of functions that are both helpful and entertaining. By utilizing LiDAR technology, the bot is able to rapidly generate three-dimensional maps of its surroundings. This function, which is frequently utilized in military settings, enables you to meticulously plan your route and steer clear of obstacles, thereby ensuring that you are able to navigate in a secure and safe manner. The LiDAR data can be analyzed with the help of algorithms that are based on artificial intelligence, which allows us to identify potential





environmental obstacles. Because it is equipped with this function, the bot is able to identify objects, people, and potential hazards, which enables it to immediately alter its path in order to safeguard against accidents.

In the use of LiDAR data, artificial intelligence algorithms are able to classify objects according to the material composition of their materials, differentiate between hard and soft materials, and perform intelligent object interaction recognition procedures. As a consequence of this, the bot will have an easier time navigating its environment and developing an understanding of it.

In the field of robotics, the bot is capable of performing tasks automatically by utilizing its sensors and manipulator arms, or by responding to commands given by humans. A great deal can be accomplished by it without requiring a great deal of intervention from a human being, such as turning lights on and off and moving objects around. It is possible for computers to comprehend and interpret spoken language thanks to a field of technology known as speech recognition. The ability of computers to communicate with humans through written or spoken language is referred to as "natural language interaction," which is the second phrase. The bot's capacity to comprehend and accurately interpret human speech enables it to perform the function of a voice assistant, which in turn simplifies the process of controlling it through voice activation. Users are able to navigate, obtain information, and complete tasks without having to touch the screen or type a single word when they activate voice commands. Voice interfaces are designed to be user-friendly for all individuals, including those with physical disabilities who may have difficulty using conventional controls. This includes the voice interface. Because of this, everyone will be able to take pleasure in a computer experience that is accessible to all. The Guidotronic Bot is equipped with features that help it become more independent, enhance its navigation capabilities, expand the range of tasks it is capable of performing, and accommodate users with a variety of requirements.

LiDAR data is utilized in this approach for the purposes of navigation and obstacle avoidance. A Journey Through the Maze: In order to evaluate the robot's ability to navigate itself, you should build a maze of varying sizes. In order to evaluate the bot's capability to navigate real-life scenarios, it is recommended that you conduct an Open Environment Test in an open area that contains a variety of shapes and degrees of difficulty. Through conducting tests in crowded areas such as streets and airports, you can determine how well the technology deals with crowds and obstacles. The purpose of the Speech Recognition Test is to determine whether or not the bot is able to comprehend spoken commands, regardless of the presence of background noise or variations in pronunciation. During the Natural Language Processing Accuracy Test, the bot is evaluated on its capacity to comprehend human speech and provide appropriate responses.

Through the User Interaction Test, the bot's responsiveness to voice commands and the accuracy of its responses are evaluated and validated before being used. The more accurate 3D mapping that is made possible by LiDAR technology contributes to the enhancement of the bot's capacities for artificial intelligence and contextual awareness. With the help of real-time mapping, the bot is able to quickly adjust to obstacles and determine the most effective routes to take. In the course of the user's interaction with the voice assistant, the artificial intelligence algorithm is able to learn from their actions and adjust itself accordingly. When LiDAR technology is used to identify potential threats, individuals experience a sense of increased safety and security. In addition, security





systems that make use of artificial intelligence are able to remotely monitor the robot. Due to the fact that LiDAR is compatible with augmented reality, it is possible to incorporate sophisticated visual overlays, which in turn enhances the level of immersion and interactivity of the experience. The bot provides users with the ability to control a wide range of Internet of Things devices through the use of voice commands and gestures, and it also functions as a conduit for connecting various smart home devices. Reminders to take medications and other information pertaining to health can be provided by the artificial intelligence algorithms of the bot. This bot has a wide range of potential applications, including the provision of customer service and the management of inventory in a variety of commercial settings, such as retail and manufacturing. An additional advantage is that it provides the elderly with company. Customers can use it to get assistance in stores and other public areas, and teachers can benefit from its use in the classroom as it allows for the clarification of concepts and the provision of examples.

5. Conclusion

The integration of artificial intelligence (AI) with Light Detection and Ranging (LiDAR) technology and the voice assistant Guidotronic Bot represents a significant progress in the interaction between humans and technology. The system combines three components—location perception, natural language understanding, and context reasoning—to generate an interface that is both intuitive and aware of the surrounding context. Consequently, it includes the capability to identify objects in real-time and has improved accessibility features for individuals with visual impairments. Additionally, it provides specific assistance through the use of LiDAR and AI technology, as well as an internet navigation system. Users rely on security measures to protect and maintain the confidentiality of their personal information. The potential ramifications of this integration have the potential to completely transform the manner in which individuals engage with various platforms, such as smart homes and retail establishments. As research and development advances, the upcoming era of voice control, bolstered by intelligent and inclusive assistance systems, will broaden its range of uses and improve its functionalities.

Declarations

Source of Funding

This study did not receive any grant from funding agencies in the public, commercial, or not-for-profit sectors.

Competing Interests Statement

The authors declare no competing financial, professional, or personal interests.

Consent for publication

The authors declare that they consented to the publication of this study.

References

[1] Al Shamsi, Jawaher Hamad, Mostafa Al-Emran & Khaled Shaalan (2022). Understanding key drivers affecting students' use of artificial intelligence-based voice assistants. Education and Information Technologies, 27(6): 8071–8091.





[2] Luo, Bei, Raymond YK Lau, Chunping Li & Yain-Whar Si (2022). A critical review of state-of-the-art chatbot designs and applications. Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery, 12(1): e1434.

[3] Dzedzickis, Andrius, Jurga Subačiūtė-Žemaitienė, Ernestas Šutinys, Urtė Samukaitė-Bubnienė & Vytautas Bučinskas (2021). Advanced applications of industrial robotics: New trends and possibilities. Applied Sciences, 12(1): 135.

[4] Sabapathy, Sundaresan, Surendar Maruthu, Suresh Kumar Krishnadhas, Ananth Kumar Tamilarasan & Nishanth Raghavan (2022). Competent and Affordable Rehabilitation Robots for Nervous System Disorders Powered with Dynamic CNN and HMM. Intelligent Systems for Rehabilitation Engineering, Pages 57–93.

[5] Khan, Rabeea, Zeeshan Yousaf, Asif Memon, Sajid Hussain & Abdul Muttalib (2021). Algorithm and Implementation of Human Following Co-bot using 2D LiDAR. Pakistan J. of Engineering & Tech., 4(2): 89–93.

[6] Chiu, Ming-Chuan, Cheng-Zhou Tsai & Yu-Chen Huang (2024). Integrating object detection and natural language processing models to build a personalized attraction recommendation agent in a smart product service system. Advanced Engineering Informatics, 61: 102484.

[7] Rettore, Paulo HL, Philipp Zißner, Mohammed Alkhowaiter, Cliff Zou & Peter Sevenich (2023). Military data space: challenges, opportunities, and use cases. IEEE Communications Magazine.

[8] Ghazali, Ezlika, Dilip S. Mutum & Na Kai Lun (2024). Expectations and beyond: The nexus of AI instrumentality and brand credibility in voice assistant retention using extended expectation-confirmation model. Journal of Consumer Behaviour, 23(2): 655–675.

[9] Bansal, Gaurang, Vinay Chamola, Amir Hussain, Mohsen Guizani & Dusit Niyato (2024). Transforming Conversations with AI—A Comprehensive Study of ChatGPT. Cognitive Computation, Pages 1–24.

[10] Shahin, Mohammad, F. Frank Chen & Ali Hosseinzadeh (2024). Harnessing customized AI to create voice of customer via GPT3. 5. Advanced Engineering Informatics, 61: 102462.

[11] Sangwan, Somin, Gurpreet Singh, Aashima Bangia & Vishwajeet Shankar Goswami (2023). Evaluation of Deep Learning Technique on Working Model of Self-driving Car—A Review. Soft Computing: Theories and Applications: Proceedings of SoCTA 2022, Pages 265–277.

[12] Meydani, Amir (2023). State-of-the-Art Analysis of the Performance of the Sensors Utilized in Autonomous Vehicles in Extreme Conditions. In International Conference on Artificial Intelligence and Smart Vehicles, Pages 137–166, Cham: Springer Nature Switzerland.

[13] Suresh Kumar, K., Helen Sulochana, C., Radhamani, A.S., & Ananth Kumar, T. (2022). Sentiment lexicon for cross-domain adaptation with multi-domain dataset in Indian languages enhanced with BERT classification model. Journal of Intelligent & Fuzzy Systems, 43(5): 6433–6450.

[14] Puntoni, Stefano, Rebecca Walker Reczek, Markus Giesler & Simona Botti (2021). Consumers and artificial intelligence: An experiential perspective. Journal of Marketing, 85(1): 131–151.



[15] Barreto, Fábio, Raphael S. de Abreu, Marina IP Josué, Eyre Brasil B. Montevecchi, Pedro Alves Valentim & Débora C. Muchaluat-Saade (2023). Providing multimodal and multi-user interactions for digital tv applications. Multimedia Tools and Applications, 82(4): 4821–4846.

[16] Barreto, Fábio, Raphael S. de Abreu, Marina IP Josué, Eyre Brasil B. Montevecchi, Pedro Alves Valentim & Débora C. Muchaluat-Saade (2023). Providing multimodal and multi-user interactions for digital tv applications. Multimedia Tools and Applications, 82(4): 4821–4846.

